



Tutorial: Tensor Approximation in Visualization and Computer Graphics

Tensor Decomposition Models

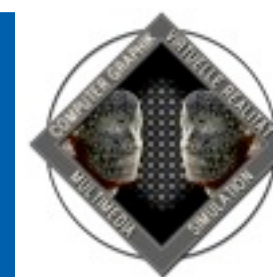
Renato Pajarola, Susanne K. Suter, and Roland Ruiters



**University of
Zurich**^{UZH}



**VISUALIZATION AND
MULTIMEDIA LAB**



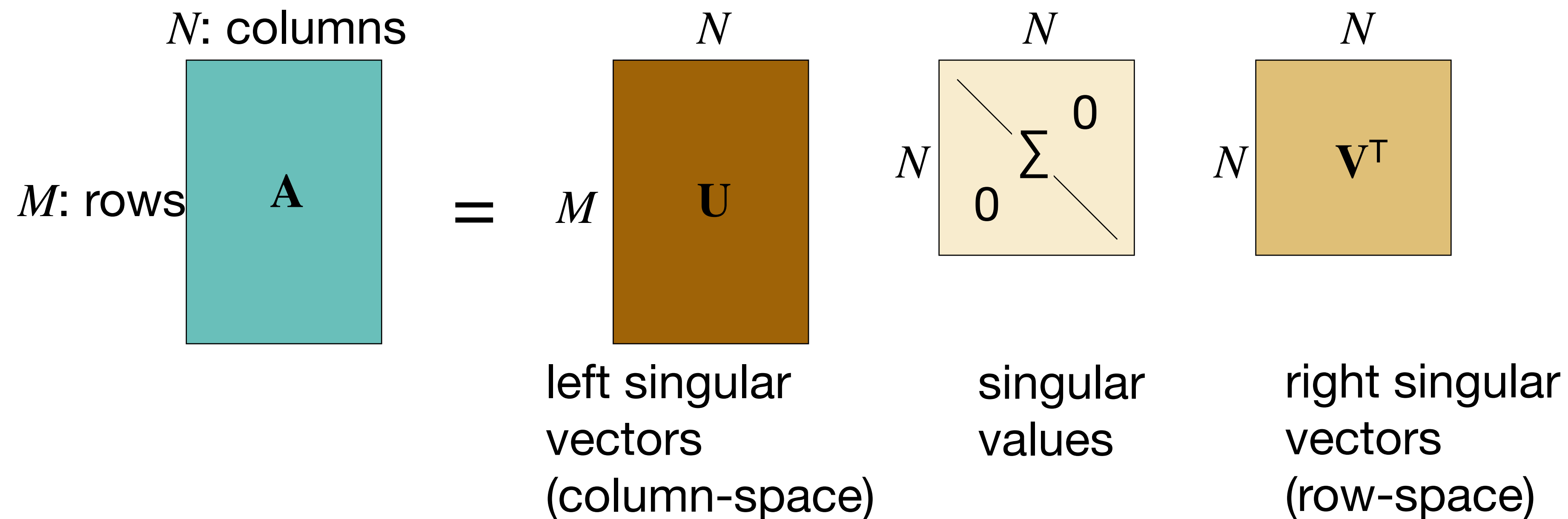
**Institute of Computer Science II
Computer Graphics**

Data Reduction and Approximation

- A fundamental concept of data reduction is to remove redundant and irrelevant information while preserving the relevant features
 - ▶ e.g. through frequency analysis by projection onto pre-defined bases, or extraction of data intrinsic principal components
 - identify spatio-temporal and frequency redundancies
 - ▶ maintain strongest and most significant signal components
- Data reduction linked to concepts and techniques of data compression, noise reduction as well as feature extraction and recognition/extraction

Data Approximation using SVD

- Singular Value Decomposition (SVD) standard tool for matrices, i.e., 2D input datasets
 - see also principal component analysis (PCA)



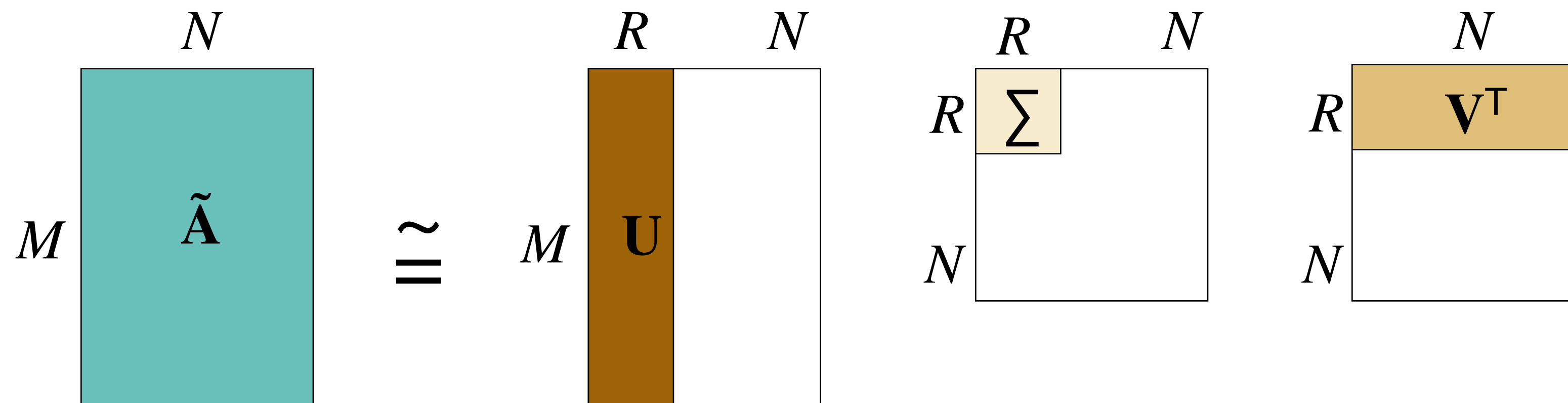
Low-rank Approximation

- Exploit ordered singular values: $s_1 \geq s_2 \geq \dots \geq s_N$
- Select first r singular values (rank reduction)

$$\begin{array}{c} M \\ \tilde{\mathbf{A}} \end{array} \begin{array}{c} N \end{array} = \begin{array}{c} M \\ \mathbf{U} \end{array} \begin{array}{c} N \end{array} \begin{array}{cc} R & N \\ R & \begin{array}{cc} \Sigma & 0 \end{array} \\ N & \begin{array}{cc} 0 & 0 \end{array} \end{array} \begin{array}{c} N \\ \mathbf{V}^T \end{array}$$

Low-rank Approximation

- Exploit ordered singular values: $s_1 \geq s_2 \geq \dots \geq s_N$
- Select first r singular values (rank reduction)
 - ▶ use only bases (singular vectors) of corresponding subspace



Matrix SVD Properties

- Matrix SVD
 - rank reducibility
 - orthonormal row/column matrices

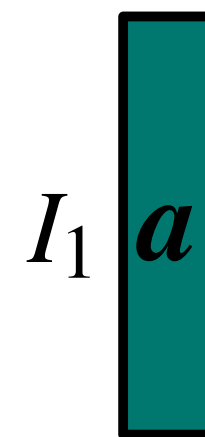
$$\begin{array}{c} N \\ \boxed{\text{A}} \\ M \end{array} = \begin{array}{c} N \\ \boxed{\text{U}} \\ M \end{array} \begin{array}{c} N \\ \boxed{\Sigma} \\ N \end{array} \begin{array}{c} N \\ \boxed{\text{V}^T} \\ N \end{array}$$

The diagram illustrates the Matrix SVD decomposition. It shows a matrix A of size $M \times N$ (teal box) being equal to the product of three matrices: U of size $M \times N$ (brown box), Σ of size $N \times N$ (light yellow box with a diagonal line and '0' at the top right and bottom left), and V^T of size $N \times N$ (yellow box).

What is a Tensor?

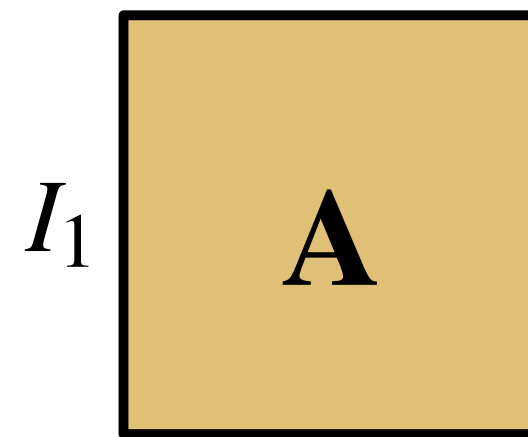


0-order tensor



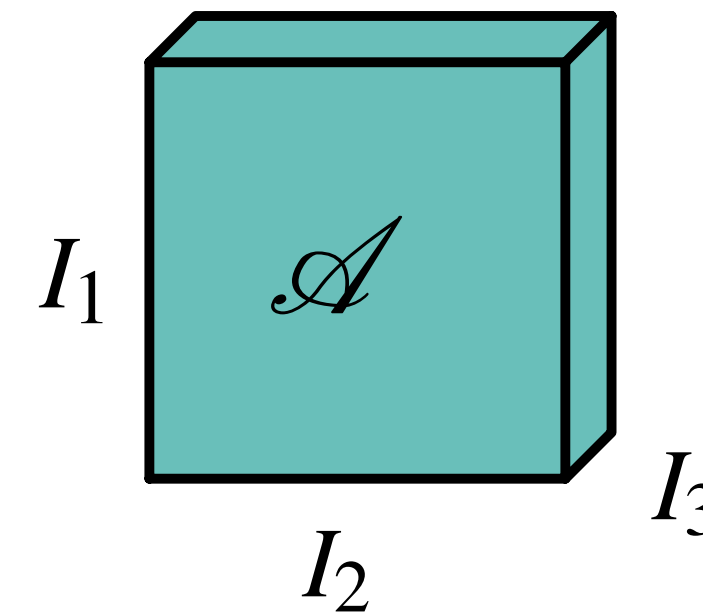
1st-order tensor

$$i_1 = 1, \dots, I_1$$



2nd-order tensor

$$i_2 = 1, \dots, I_2$$



3rd-order tensor

$$i_3 = 1, \dots, I_3$$

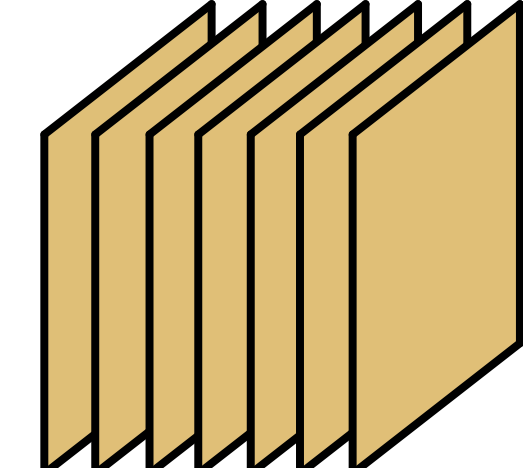
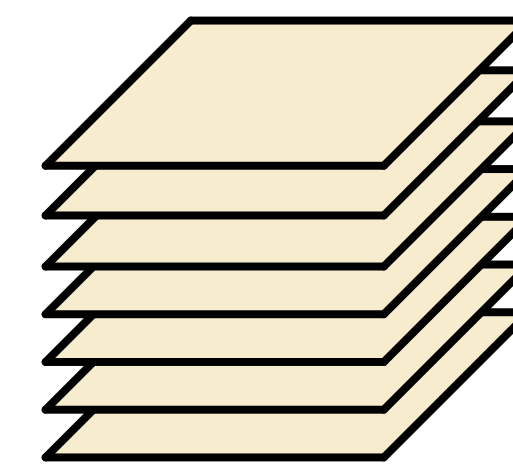
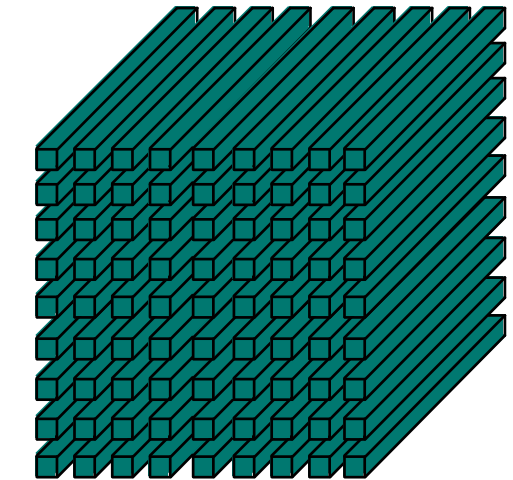
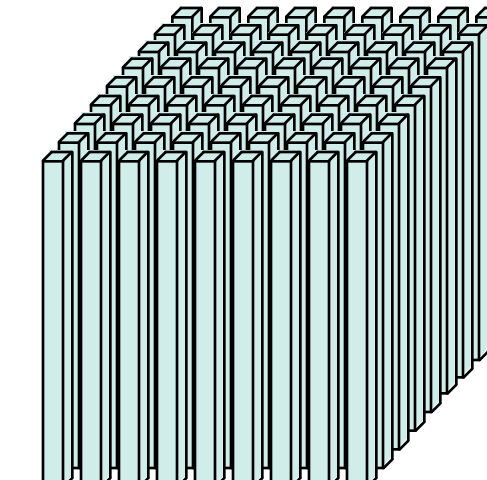
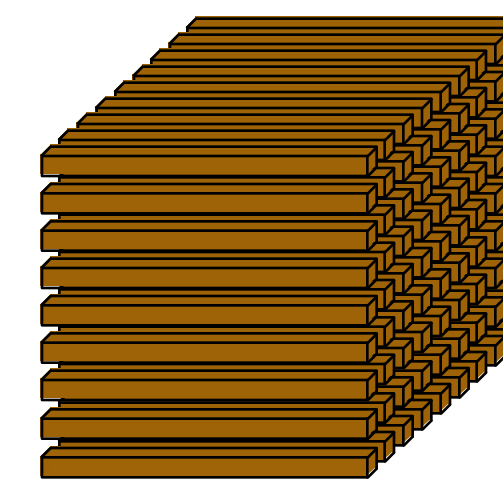
$$\mathcal{A}^{N\text{-th order}} \in \mathbb{R}^{I_1 \times I_2 \cdots \times I_N}$$

...

- Data sets are often multidimensional arrays (tensors)
 - images, image collections, video, volume data etc.

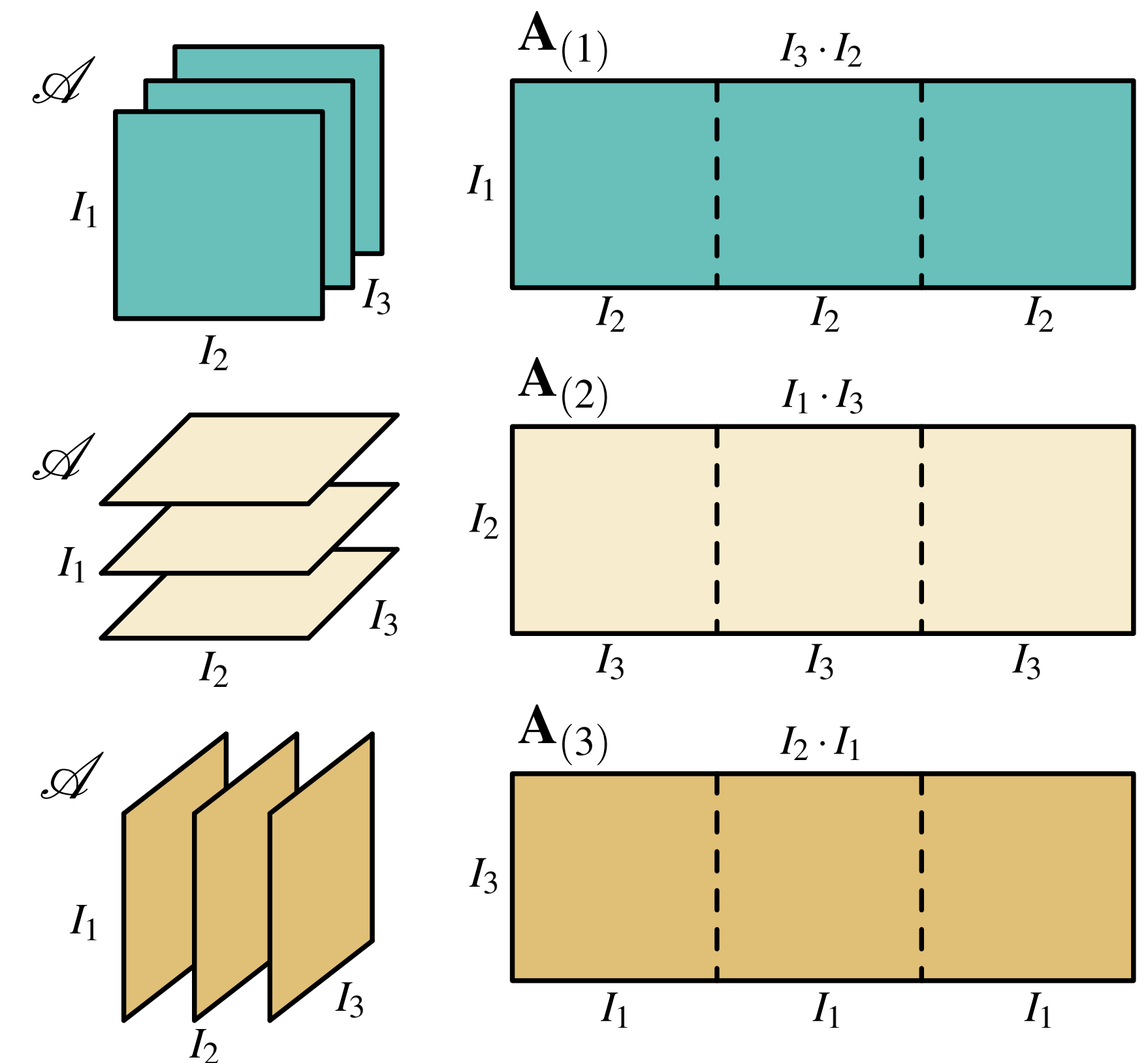
Fibers and Slices

- Individual elements of a vector \mathbf{a} are given by a_{i1} , from a matrix \mathbf{A} by $a_{i1,i2}$ and from a tensor \mathcal{A} by $a_{i1,i2,i3}$
- The generalization of rows, columns (and tubes) is a *fiber* in a particular mode
- Two dimensional sections of a tensor are called slices
 - frontal, horizontal and lateral for $\mathcal{A} \in \mathbb{R}^3$



Unfolding and Ranks

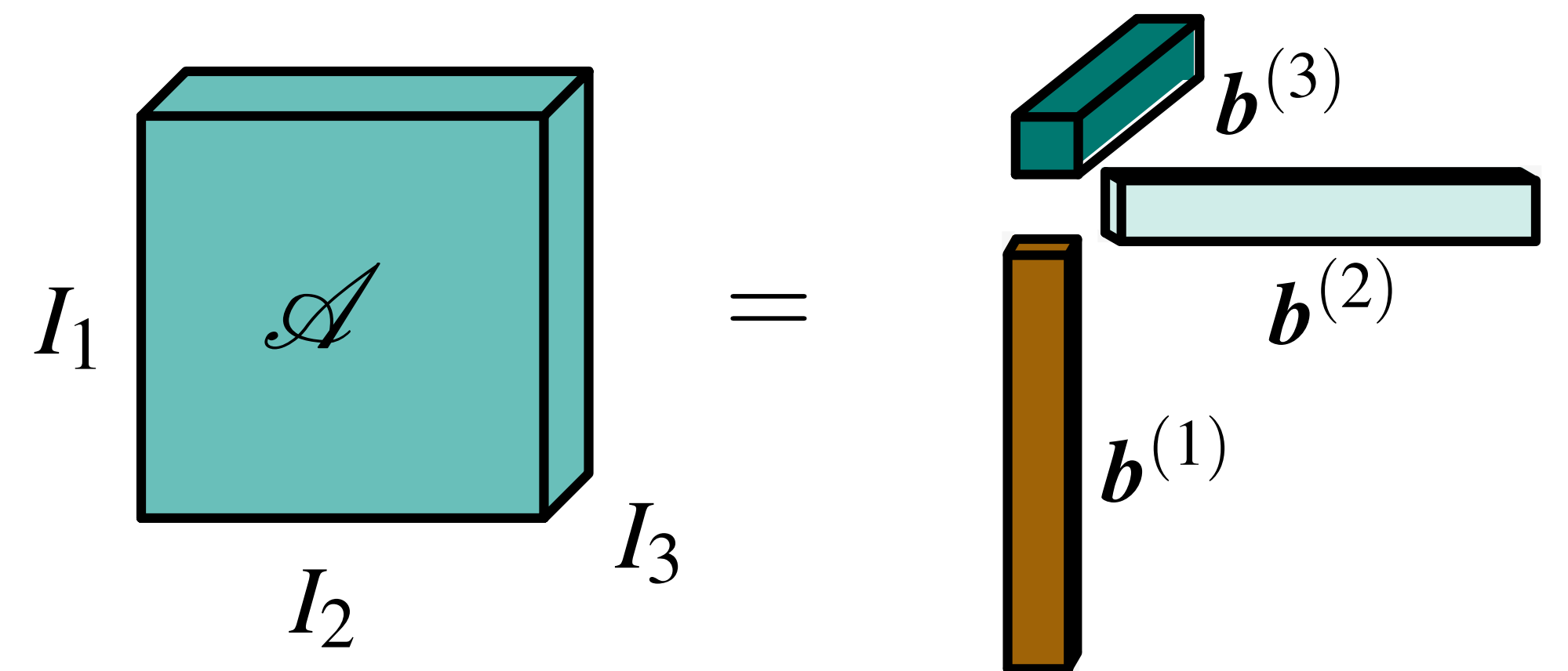
- Operations with tensors often performed as matrix operations using unfolded tensor representations
 - ▶ different tensor unfolding strategies possible
- Forward cyclic unfolding $\mathbf{A}_{(n)}$ of a 3rd order tensor \mathcal{A} (or 3D volume)
- The n -rank of a tensor is typically defined on an unfolding
 - ▶ n -rank $R_n = \text{rank}_n(\mathcal{A}) = \text{rank}(\mathbf{A}_{(n)})$
 - ▶ multilinear rank- (R_1, R_2, \dots, R_N) of \mathcal{A}



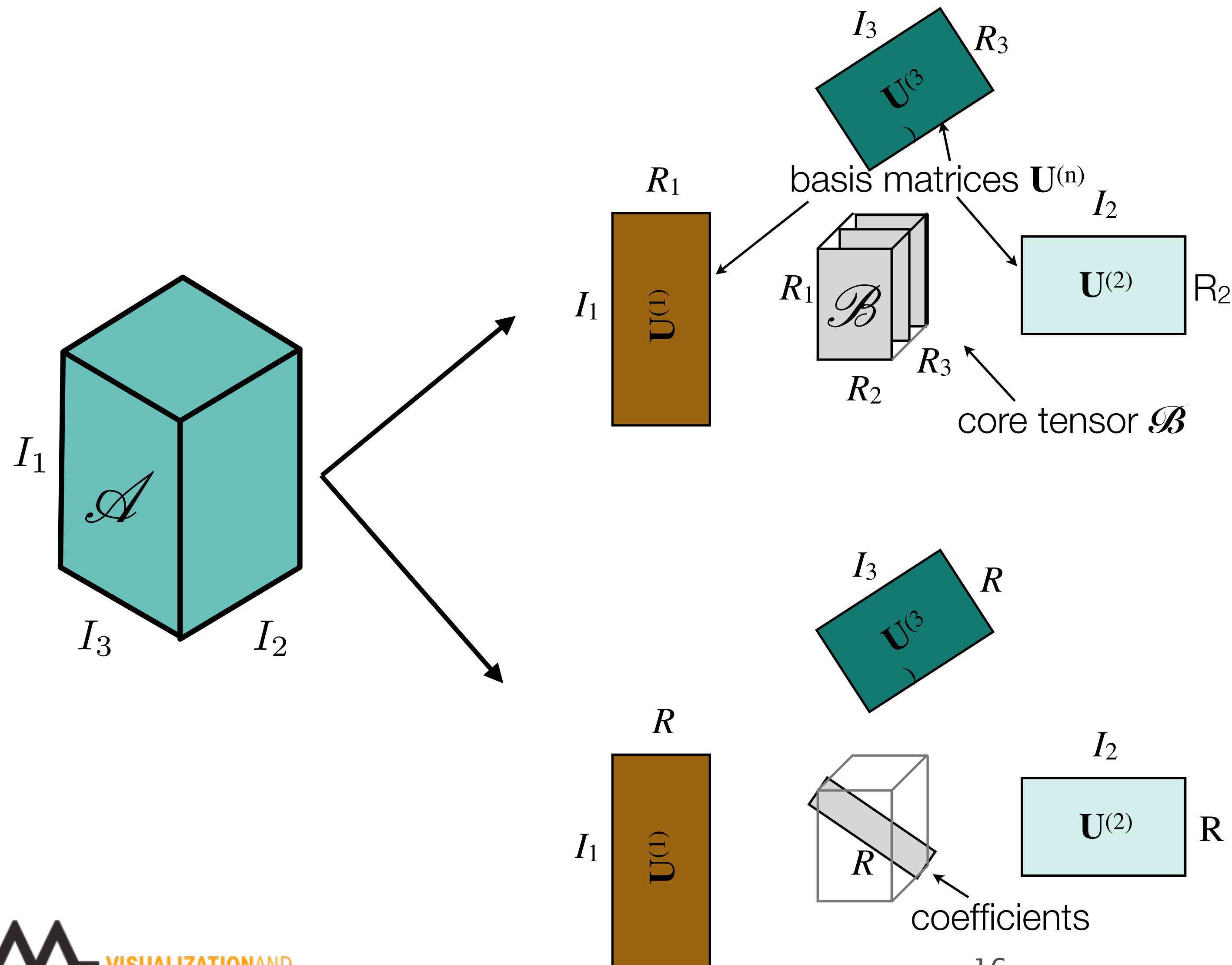
Rank-one Tensor

- N -mode tensor $\mathcal{A} \in \mathbb{R}^{I_1 \times \dots \times I_N}$ that can be expressed as the outer product of N vectors
 - Kruskal tensor
- Useful to understand principles of rank-reduced tensor reconstruction
 - linear combination of rank-one tensors

$$\mathcal{A} = \mathbf{b}^{(1)} \circ \mathbf{b}^{(2)} \circ \dots \circ \mathbf{b}^{(N)}$$



Tensor Decomposition Models



Tucker

- Three-mode factor analysis (**3MFA/Tucker3**) [Tucker, 1964+1966]
- Higher-order SVD (**HOSVD**) [De Lathauwer et al., 2000a]

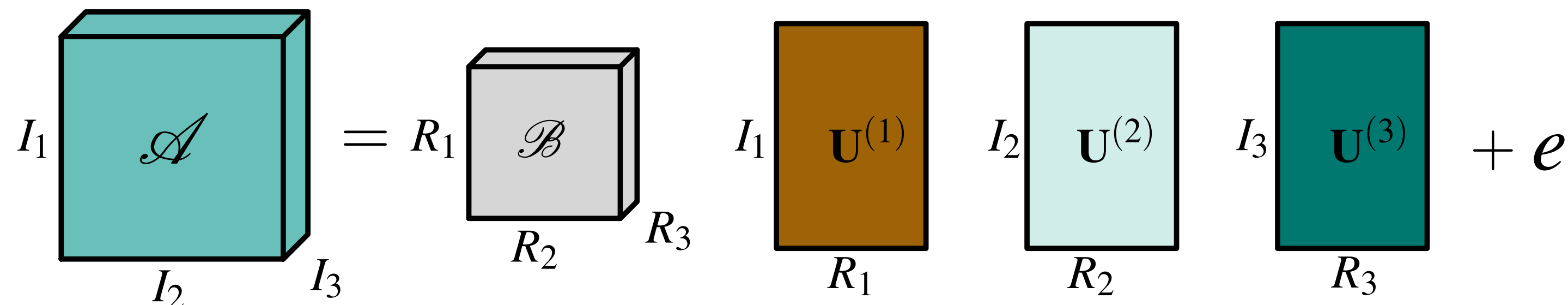
CP

- **PARAFAC** (parallel factors) [Harshman, 1970]
- **CANDECOMP** (CAND) (canonical decomposition) [Carroll & Chang, 1970]

Tucker Model

- Higher order tensor $\mathcal{A} \in \mathbb{R}^{I_1 \times \dots \times I_N}$ represented as a product of a core tensor $\mathcal{B} \in \mathbb{R}^{R_1 \times \dots \times R_N}$ and N factor matrices $\mathbf{U}^{(n)} \in \mathbb{R}^{I_n \times R_n}$
 - using n -mode products \times_n

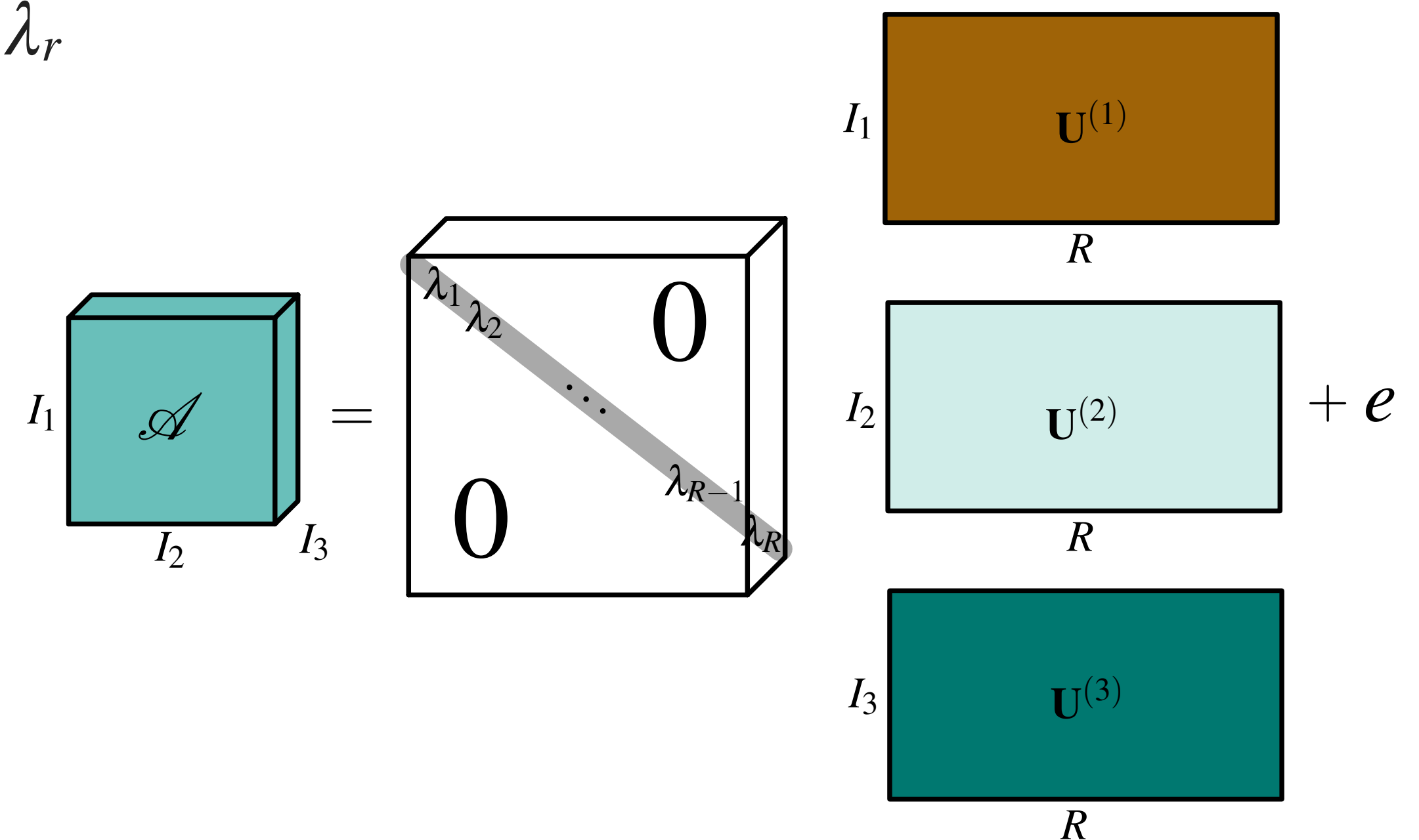
$$\mathcal{A} = \mathcal{B} \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \cdots \times_N \mathbf{U}^{(N)} + \varepsilon$$



CANDECOMP-PARAFAC Model

- *Canonical decomposition or parallel factor analysis* model (CP)
- Higher order tensor \mathcal{A} factorized into a sum of rank-one tensors
 - ▶ normalized column vectors $\mathbf{u}_r^{(n)}$ define factor matrices $\mathbf{U}^{(n)} \in \mathbb{R}^{I_n \times R}$ and weighting factors λ_r

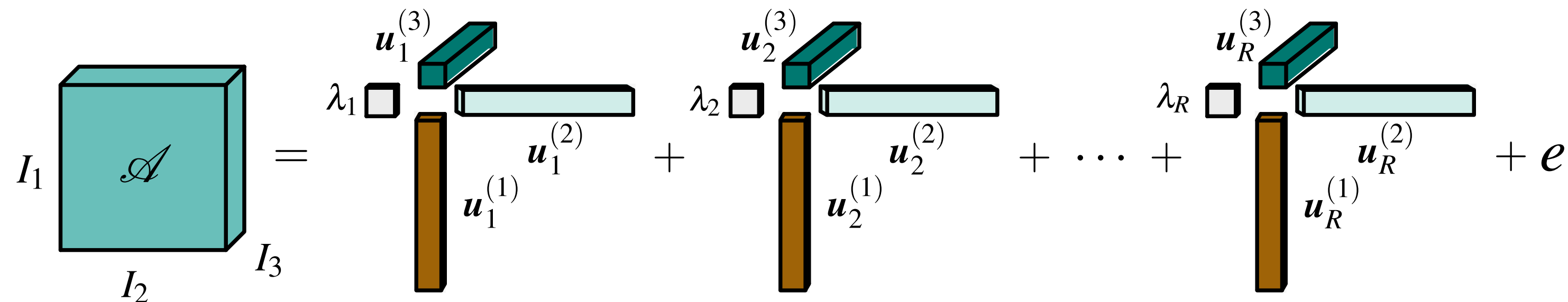
$$\mathcal{A} = \sum_{r=1}^R \lambda_r \cdot \mathbf{u}_r^{(1)} \circ \mathbf{u}_r^{(2)} \circ \dots \circ \mathbf{u}_r^{(N)} + \mathbf{e}$$



Linear Combination of Rank-one Tensors

- The CP model is defined as a linear combination of rank-one tensors

$$\mathcal{A} = \sum_{r=1}^R \lambda_r \cdot \mathbf{u}_r^{(1)} \circ \mathbf{u}_r^{(2)} \circ \dots \mathbf{u}_r^{(N)} + \varepsilon$$

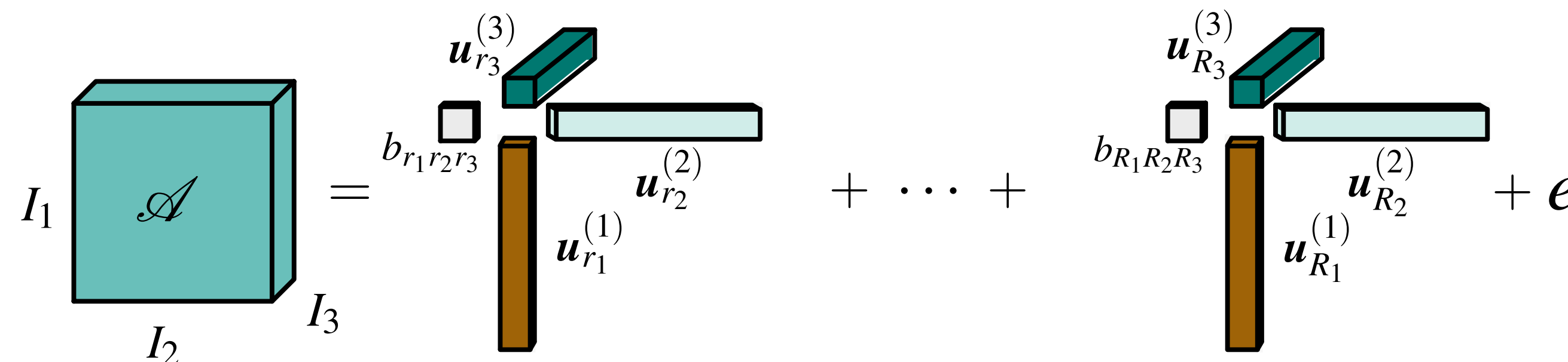


$$\begin{matrix} I_1 \\ \mathcal{A} \\ I_2 \quad I_3 \end{matrix} = \lambda_1 \begin{matrix} u_1^{(3)} \\ \lambda_1 \\ u_1^{(1)} \end{matrix} u_1^{(2)} + \lambda_2 \begin{matrix} u_2^{(3)} \\ \lambda_2 \\ u_2^{(1)} \end{matrix} u_2^{(2)} + \dots + \lambda_R \begin{matrix} u_R^{(3)} \\ \lambda_R \\ u_R^{(1)} \end{matrix} u_R^{(2)} + \varepsilon$$

Linear Combination of Rank-one Tensors

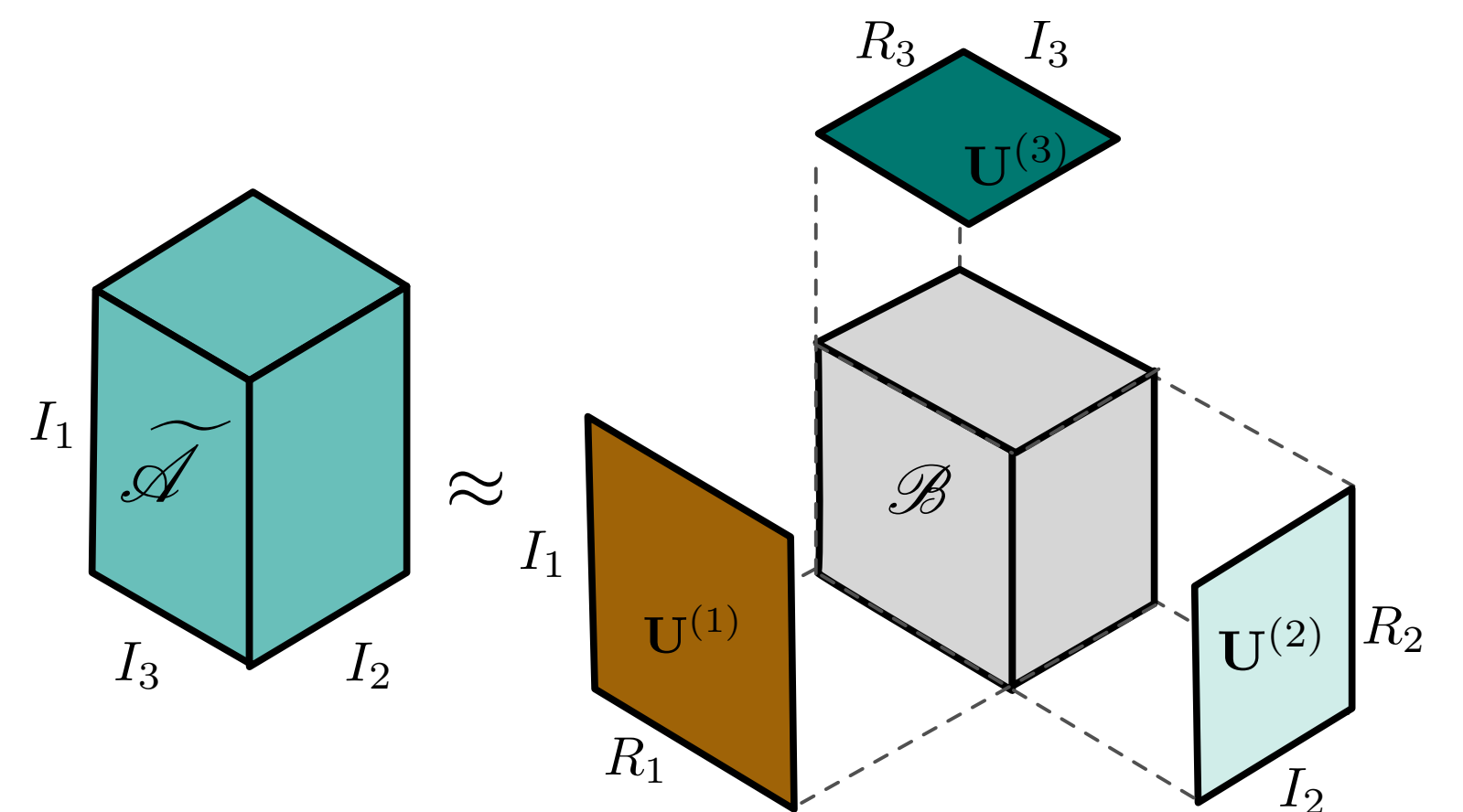
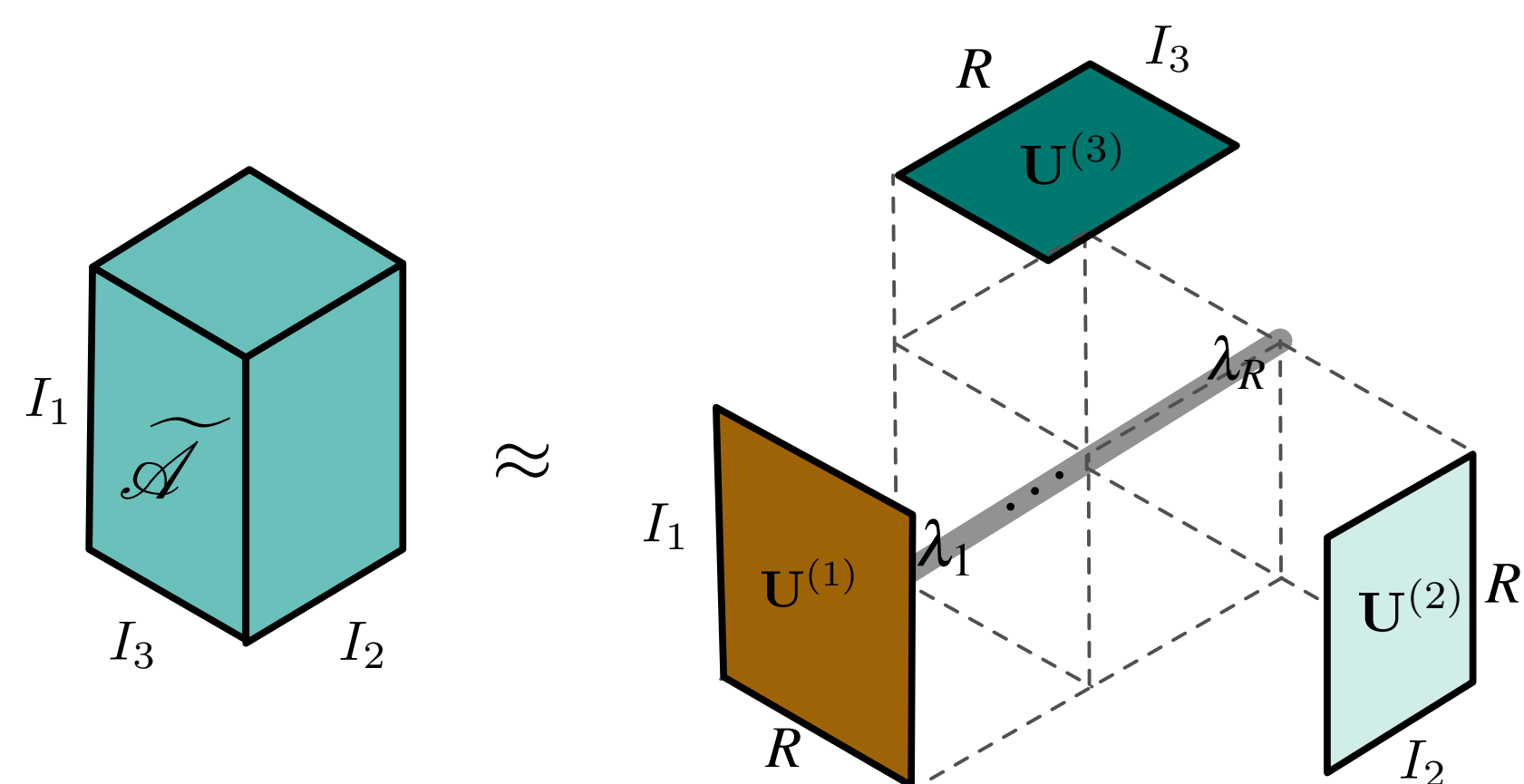
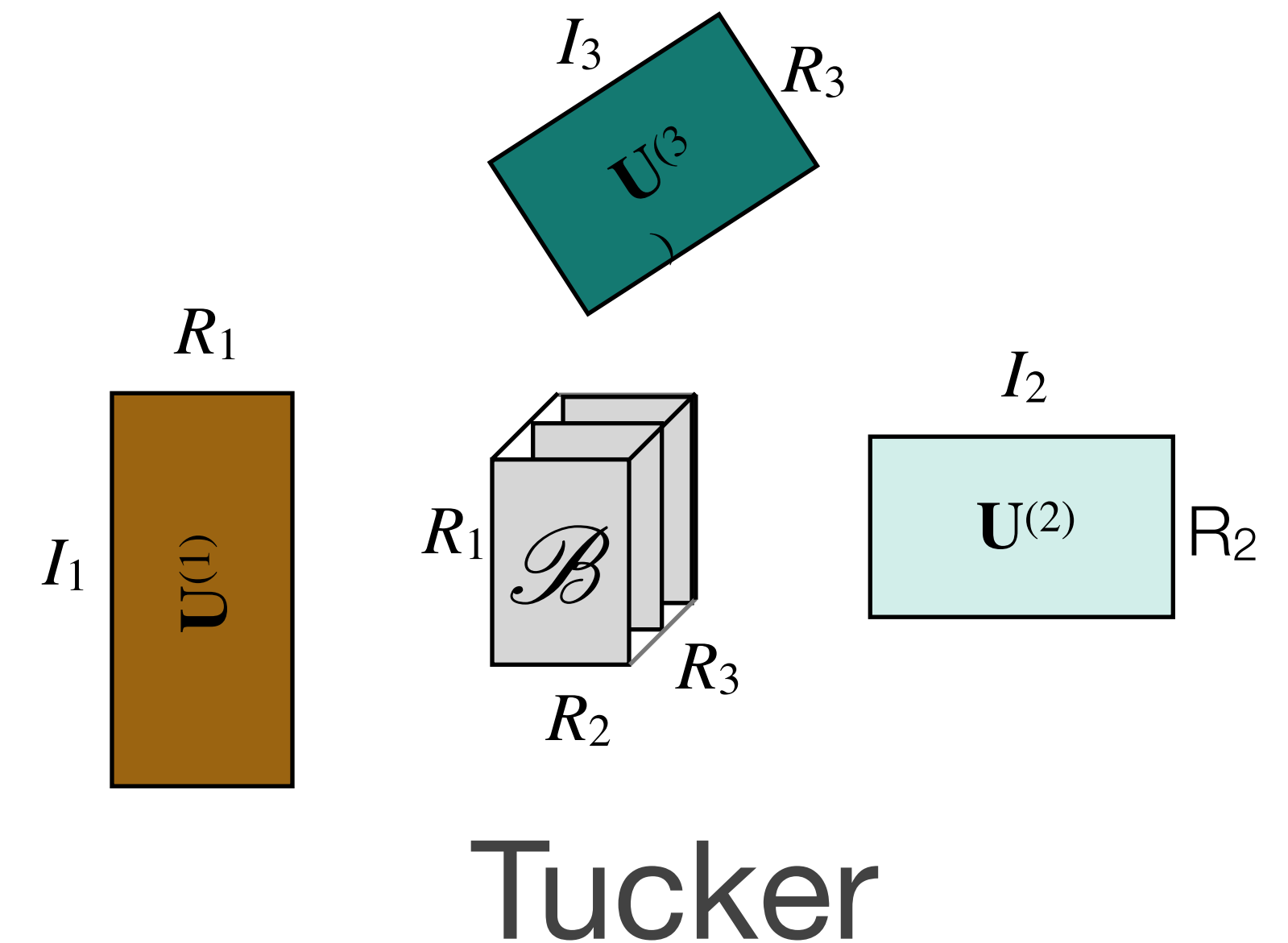
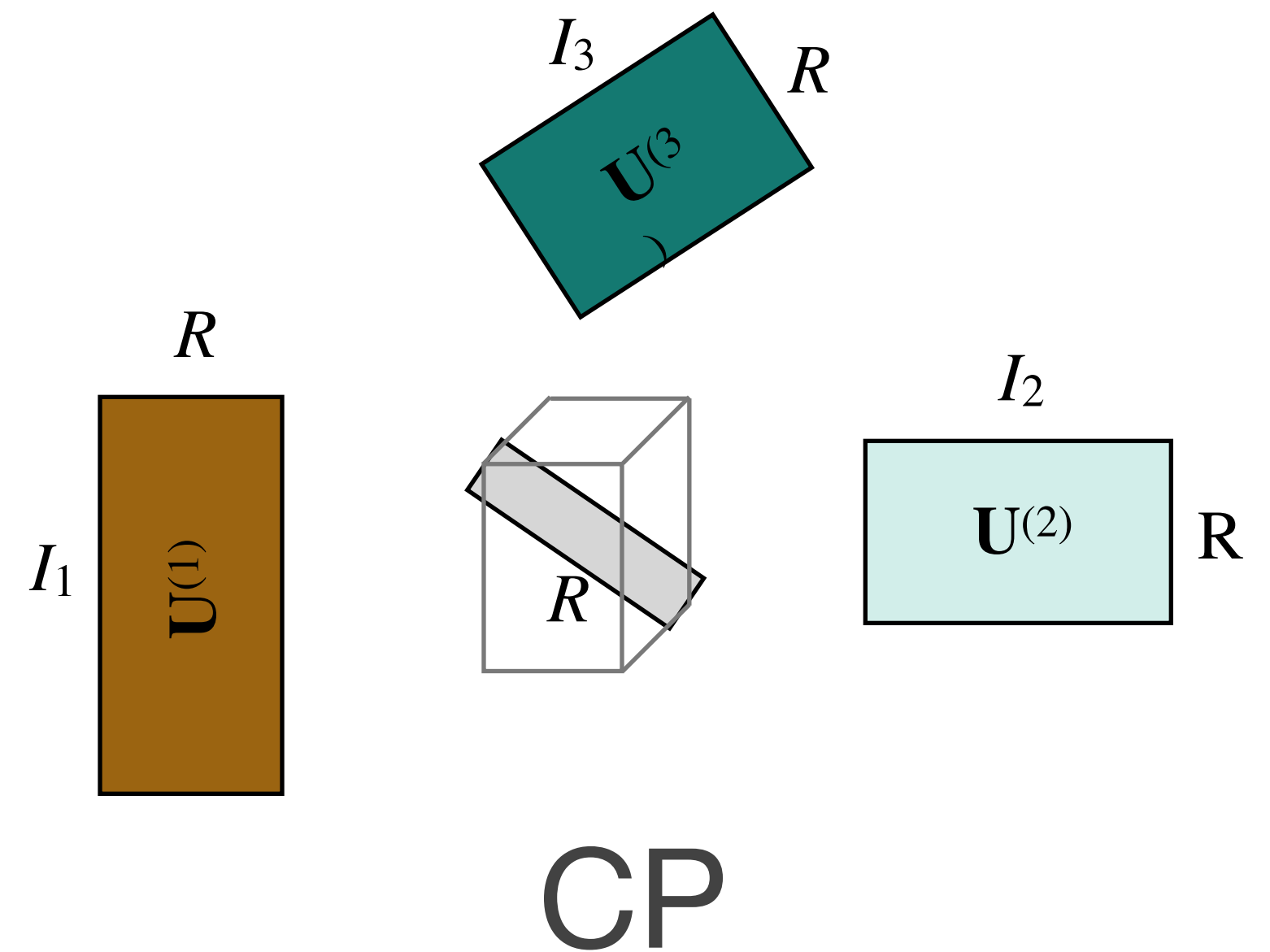
- The CP model is defined as a linear combination of rank-one tensors
- The Tucker model can be interpreted as linear combination of rank-one tensors

$$\mathcal{A} = \sum_{r_1=1}^{R_1} \sum_{r_2=1}^{R_2} \cdots \sum_{r_N=1}^{R_N} b_{r_1 r_2 \dots r_N} \cdot \mathbf{u}_{r_1}^{(1)} \circ \mathbf{u}_{r_2}^{(2)} \circ \dots \circ \mathbf{u}_{r_N}^{(N)} + \varepsilon$$



$$\mathcal{A} = \sum_{r_1, r_2, r_3} b_{r_1 r_2 r_3} \mathbf{u}_{r_1}^{(1)} \circ \mathbf{u}_{r_2}^{(2)} \circ \mathbf{u}_{r_3}^{(3)} + \dots + \mathbf{u}_{R_1}^{(1)} \circ \mathbf{u}_{R_2}^{(2)} \circ \mathbf{u}_{R_3}^{(3)} + \varepsilon$$

CP a Special Case of Tucker



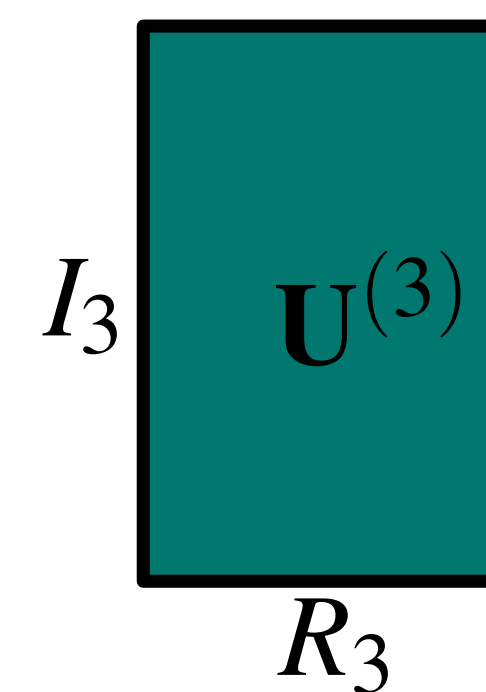
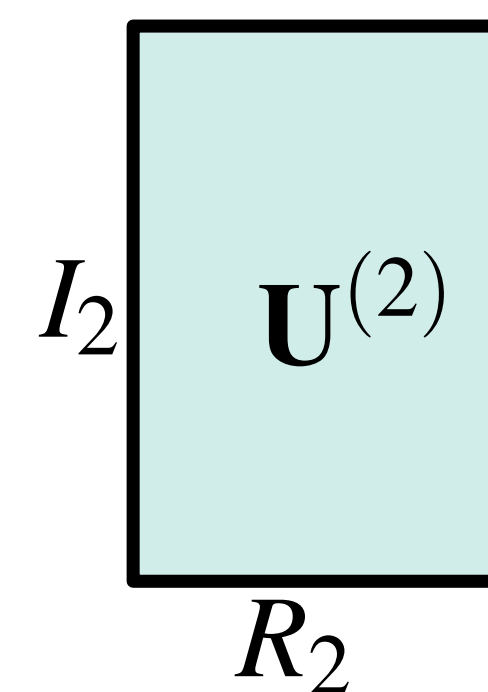
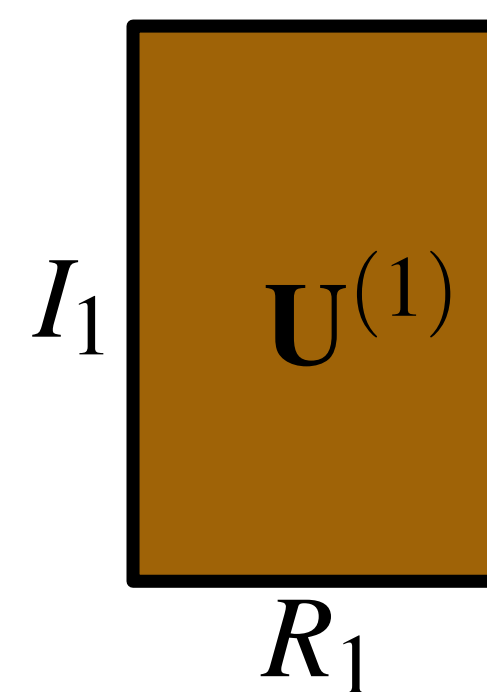
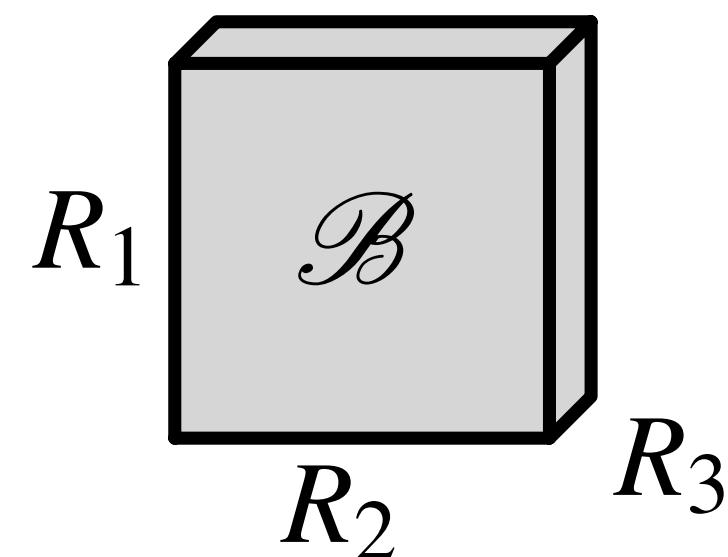
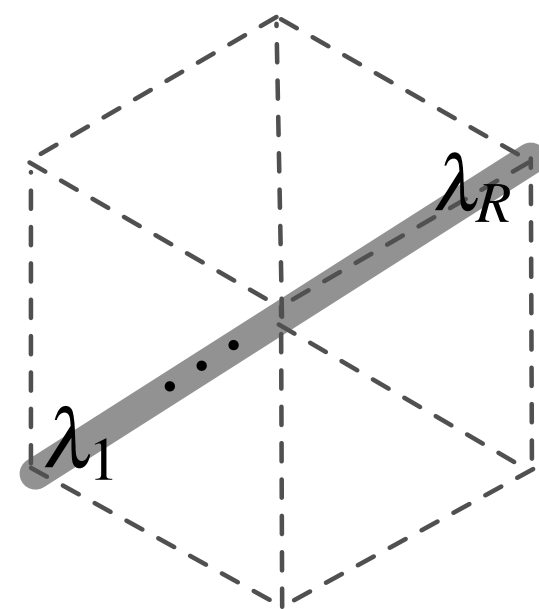
Generalizations

- Any special form of core and corresponding factor matrices
 - e.g. blocks along diagonal

$$\begin{array}{c} I_1 \\ \text{[teal cube with } \mathcal{A} \text{]} \\ I_2 \quad I_3 \end{array} = \begin{array}{c} \text{[white cube with } \mathcal{B}_1, \mathcal{B}_P \text{ and } 0 \text{ blocks]} \\ \text{[diagonal blocks } \mathcal{B}_1, \mathcal{B}_P \text{ and } 0 \text{]} \end{array} = \begin{array}{c} I_1 \\ \text{[brown blocks } \mathbf{U}_1^{(1)}, \mathbf{U}_2^{(1)}, \dots, \mathbf{U}_P^{(1)} \text{]} \\ R \end{array} + e + \begin{array}{c} I_2 \\ \text{[light blue blocks } \mathbf{U}_1^{(2)}, \mathbf{U}_2^{(2)}, \dots, \mathbf{U}_P^{(2)} \text{]} \\ R \end{array} + \begin{array}{c} I_3 \\ \text{[teal blocks } \mathbf{U}_1^{(3)}, \mathbf{U}_2^{(3)}, \dots, \mathbf{U}_P^{(3)} \text{]} \\ R \end{array}$$

Reduced Rank Approximation

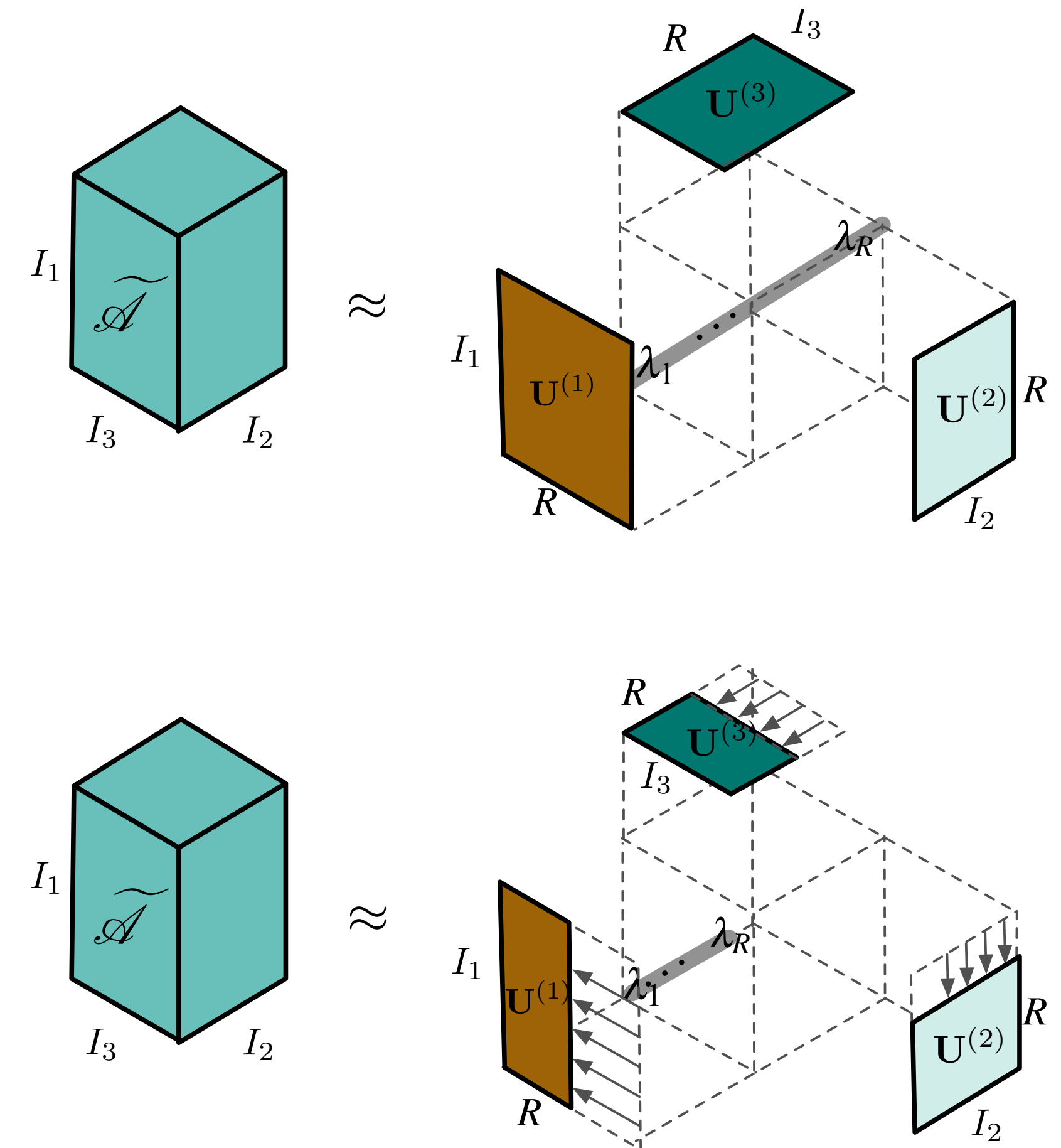
- Full reconstruction using a Tucker or CP model may require excessively many coefficients and wide factor matrices
 - ▶ large rank values R (CP), or $R_1, R_2 \dots R_N$ (Tucker)
- Quality of approximation increases with the rank, and number of column vectors of the factor matrices
 - ▶ best possible fit of these bases matrices discussed later



Rank- R Approximation

- Approximation of a tensor as a linear combination of rank-one tensors using a limited number R of terms
 - CP model of limited rank R

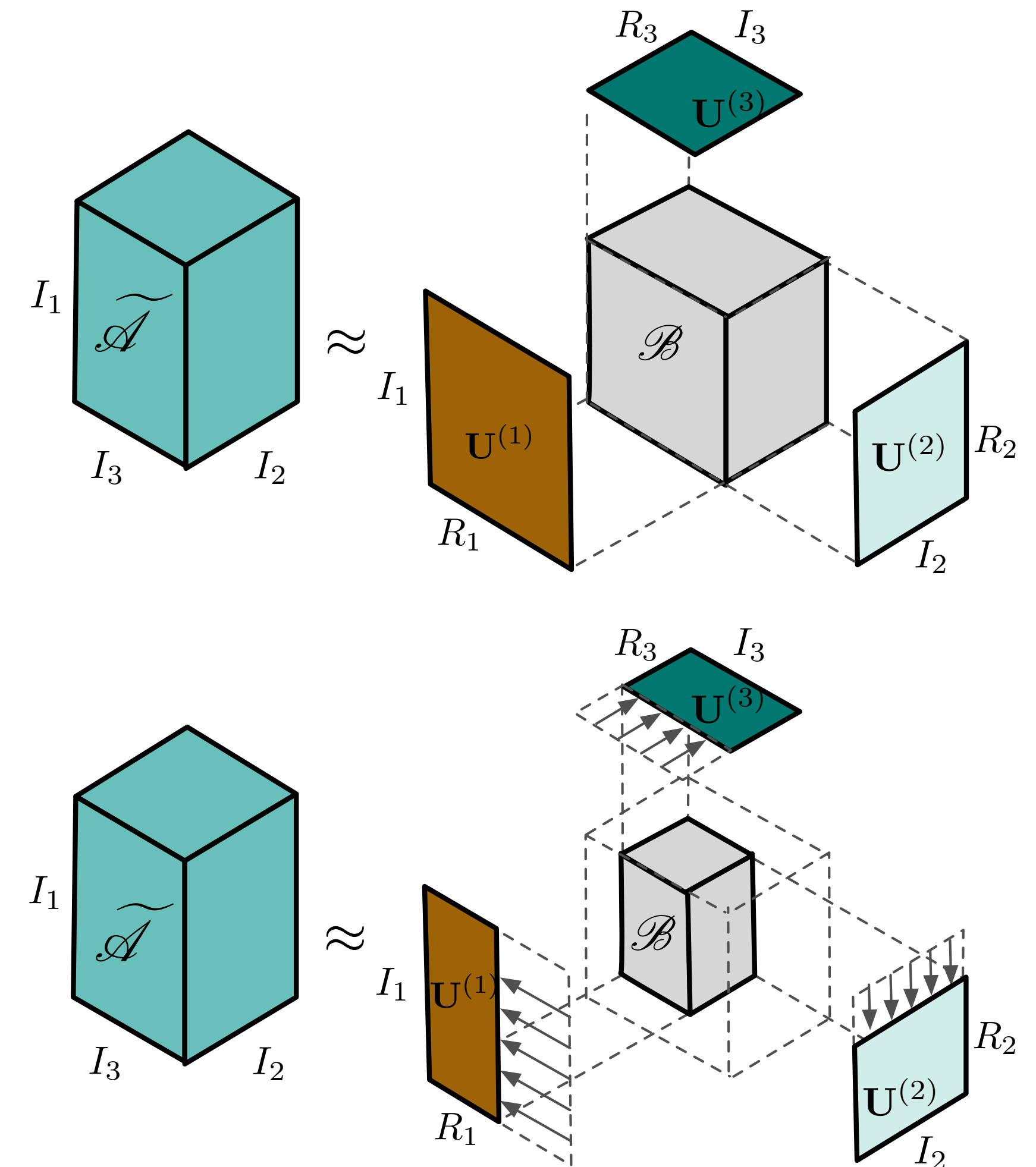
$$\tilde{\mathcal{A}} = \sum_{r=1}^R \lambda_r \cdot \mathbf{u}_r^{(1)} \circ \mathbf{u}_r^{(2)} \circ \dots \circ \mathbf{u}_r^{(N)}$$



Rank- (R_1, R_2, \dots, R_N) Approximation

- Decomposition into a tensor with reduced, lower multilinear rank (R_1, R_2, \dots, R_N)
 - ▶ $\text{rank}_n(\tilde{\mathcal{A}}) = R_n \leq \text{rank}_n(\mathcal{A}) = \text{rank}(\mathbf{A}_{(n)})$
- n -mode products of factor matrices and core tensor in a given reduced rank space
 - ▶ Tucker model with limited ranks R_i

$$\tilde{\mathcal{A}} = \mathcal{B} \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \cdots \times_N \mathbf{U}^{(N)}$$

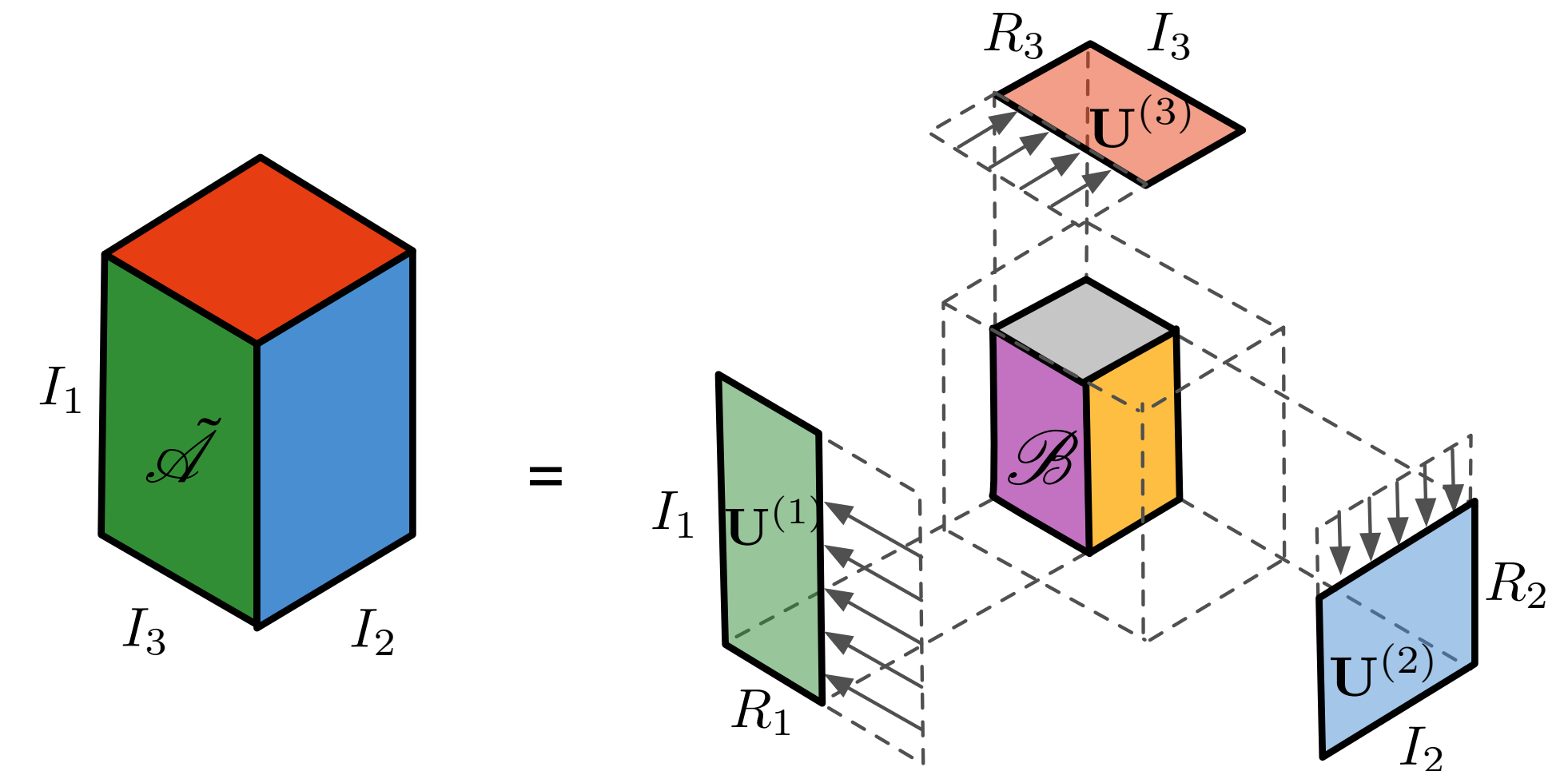


Best Rank Approximation

- Rank reduced approximation that minimizes least-squares cost

$$\mathcal{\tilde{A}} = \arg \min(\mathcal{\tilde{A}}) \left\| \mathcal{A} - \mathcal{\tilde{A}} \right\|^2$$

- Alternating least squares (ALS) iterative algorithm that converges to a minimum approximation error based on the Frobenius norm $\|\dots\|_F$
 - rotation of components in basis matrices



$$\mathcal{\tilde{A}} = \mathcal{B} \times_1 \mathbf{U}^{(1)} \times_2 \mathbf{U}^{(2)} \times_3 \mathbf{U}^{(3)}$$

typical high-quality data reduction:
 $R_k \leq I_k / 2$

Generalization of the Matrix SVD

$$\begin{matrix} M \\ N \end{matrix} \mathbf{A} = \begin{matrix} M \\ N \end{matrix} \mathbf{U} \begin{matrix} N \\ N \end{matrix} \mathbf{\Sigma} \begin{matrix} N \\ N \end{matrix} \mathbf{V}^T$$

higher orders

CP model

$$\begin{matrix} I_1 \\ I_2 \\ I_3 \end{matrix} \mathcal{A} = \begin{matrix} I_1 \\ I_2 \\ I_3 \end{matrix} \begin{matrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \\ & & & \lambda_{R-1} \\ 0 & & & & \lambda_R \end{matrix} \begin{matrix} I_1 \\ I_2 \\ I_3 \end{matrix} \begin{matrix} \mathbf{U}^{(1)} \\ \mathbf{U}^{(2)} \\ \mathbf{U}^{(3)} \end{matrix} + e$$

Tucker model

$$\begin{matrix} I_1 \\ I_2 \\ I_3 \end{matrix} \mathcal{A} = \begin{matrix} R_1 \\ R_2 \\ R_3 \end{matrix} \mathcal{B} \begin{matrix} I_1 \\ I_2 \\ I_3 \end{matrix} \begin{matrix} \mathbf{U}^{(1)} \\ \mathbf{U}^{(2)} \\ \mathbf{U}^{(3)} \end{matrix} + e$$